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**BEST APPROXIMATION  
IN CHEBYSHEV SUBSPACES OF  $\mathcal{L}(l_1^n, l_1^n)$**

**Abstract.** Chebyshev subspaces of  $\mathcal{L}(l_1^n, l_1^n)$  are studied. A construction of a  $k$ -dimensional Chebyshev (not interpolating) subspace is given.

**Keywords:** interpolating subspace, Chebyshev subspace, strongly unique best approximation.

**Mathematics Subject Classification:** 41A50, 41A52.

1. INTRODUCTION

Let  $\mathbb{K}$  be the field of real or complex numbers and let  $(X, \|\cdot\|)$  be a normed space over  $\mathbb{K}$ . Let  $extS_{X^*}$  denote the set of all extreme points of  $S_{X^*}$ , where  $S_{X^*}$  is the unit sphere in  $X^*$ .

For any  $x \in X$ , we put

$$E(x) = \{f \in extS_{X^*} : f(x) = \|x\|\} \tag{1}$$

and with any  $Y \subset X$  we associate the set

$$P_Y(x) = \{y \in Y : \|x - y\| = dist(x, Y)\}.$$

Note that, by the Hahn-Banach and Krein-Milman Theorems,  $E(x) \neq \emptyset$ .

A linear subspace  $Y \subset X$  is called a Chebyshev subspace if for any  $x \in X$  the set  $P_Y(x)$  contains one element only.

If  $Y$  is a linear subspace of  $X$ , then the following holds

**Theorem 1 ([3]).** *Assume  $X$  is a normed space,  $Y \subset X$  is its linear subspace, and let  $x \in X \setminus Y$ . Then  $y_0 \in P_Y(x)$  if and only if for every  $y \in Y$  there exists  $f \in E(x - y_0)$  with  $ref(y) \leq 0$ .*

Let us recall a well-known definition

**Definition 1** (see e.g. [7]). An element  $y_0 \in Y$  is called a strongly unique best approximation for  $x \in X$  if and only if there exists  $r > 0$  such that for every  $y \in Y$ ,

$$\|x - y\| \geq \|x - y_0\| + r\|y - y_0\|.$$

The largest constant  $r$  satisfying the above inequality is called the strong unicity constant. There exist two main applications of the strong unicity constant:

1. The error estimate of the Remez algorithm (see e.g. [10]).
2. The Lipschitz continuity of the best approximation mapping at  $x_0$  (assuming that there exists a strongly unique best approximation to  $x_0$ ) (see e.g. [5, 8, 9]).

The following holds true:

**Theorem 2** ([14]). *Let  $x \in X \setminus Y$  and let  $Y$  be a linear subspace of  $X$ . Then  $y_0 \in Y$  is a strongly unique best approximation for  $x$  with a constant  $r > 0$  if and only if for every  $y \in Y$  there exists  $f \in E(x - y_0)$  with  $\text{ref}(y) \leq -r\|y\|$ .*

In this paper, we consider  $X = \mathcal{L}(l_1^n, l_1^n)$ ,  $n > 1$  (the space of all linear and continuous operators from  $l_1^n$  to  $l_1^n$  equipped with the operator norm denoted by  $\|\cdot\|_{op}$ ), where

$$l_1^n = \left\{ x = (x_1, x_2, \dots, x_n) \in \mathbb{R}^n : \|x\| := \sum_{i=1}^n |x_i| \right\}.$$

It is known [11] that for any operator  $A \in \mathcal{L}(l_1^n, l_1^n)$ :

$$\|A\|_{op} = \max_{x \in \text{ext}S_{l_1^n}} \|Ax\|.$$

Since (see [1])

$$\text{ext}S_{l_1^n} = \{e_i = (\delta_{1i}, \delta_{2i}, \dots, \delta_{ni}), i = 1, 2, \dots, n\},$$

then for any  $A = [a_{ij}]_{i,j=1,2,\dots,n} \in \mathcal{L}(l_1^n, l_1^n)$ , we obtain

$$\|A\|_{op} = \max \left\{ \sum_{i=1}^n |a_{i1}|, \dots, \sum_{i=1}^n |a_{in}| \right\}.$$

The aim of this paper is to show that, for any  $k \leq n$ , there exists a  $k$ -dimensional Chebyshev subspace of  $\mathcal{L}(l_1^n, l_1^n)$  which is not an interpolating subspace.

This result is quite different from the result obtained for the space  $\mathcal{L}(l_1^n, c_0)$  (see [6]), where any finite dimensional Chebyshev subspace is an interpolating subspace. Additionally, as the space  $\mathcal{L}(l_1^n, l_1^n)$  is a finite dimensional space, we get (see [13]) that the unicity of best approximation is equivalent to the strong unicity of best approximation.

2. ONE-DIMENSIONAL CHEBYSHEV SUBSPACES OF  $\mathcal{L}(l_1^n, l_1^n)$ 

Let an operator  $A \in \mathcal{L}(l_1^n, l_1^n)$  be represented by a matrix  $[a_{ij}]_{i,j=1,2,\dots,n}$ . Since (see [4, 12])

$$\text{ext}S_{\mathcal{L}^*(l_1^n, l_1^n)} = \text{ext}S_{l_\infty^n} \otimes \text{ext}S_{l_1^n}, \quad (2)$$

where

$$l_\infty^n = \left\{ x = (x_1, x_2, \dots, x_n) : \|x\| := \max_{i \in \{1, 2, \dots, n\}} |x_i| \right\}$$

we get

$$\text{ext}S_{\mathcal{L}^*(l_1^n, l_1^n)} = \{x \otimes e_j : j = 1, 2, \dots, n\},$$

where  $e_j = (\delta_{1j}, \delta_{2j}, \dots, \delta_{nj})$ ,  $j = 1, 2, \dots, n$ , and  $x = (x_1, x_2, \dots, x_n)$ ,  $x_i \in \{-1, 1\}$ ,  $i = 1, 2, \dots, n$ . So, for any operator  $A \in \mathcal{L}(l_1^n, l_1^n)$  represented by a matrix  $[a_{ij}]_{i,j=1,2,\dots,n}$ , there is

$$(x \otimes e_j)(A) = \sum_{i=1}^n x_i a_{ij}.$$

Since  $E(A) \neq \emptyset$ , then by (1) and (2), we get that there exist  $x \in l_\infty^n$  and  $j \in \{1, 2, \dots, n\}$  such that

$$\|A\|_{op} = (x \otimes e_j)(A).$$

Let us recall [2] that a  $k$ -dimensional subspace  $\mathcal{V}$  of the normed space  $X$  is called an interpolating subspace if and only if for any linearly independent  $f_1, f_2, \dots, f_k \in \text{ext}S_{X^*}$  and for any  $v \in \mathcal{V}$ , the following holds: if  $f_i(v) = 0$ ,  $i = 1, 2, \dots, k$ , then  $v = 0$ . It is known [2] that any finite dimensional interpolating subspace is a finite dimensional Chebyshev subspace.

**Theorem 3.** *Let  $\mathcal{V} \subset \mathcal{L}(l_1^n, l_1^n)$  be a  $k$ -dimensional ( $k < n^2$ ) subspace such that  $\mathcal{V} = \text{lin}\{V_1, V_2, \dots, V_k\}$ ,  $V_m \in \mathcal{L}(l_1^n, l_1^n)$ ,  $m = 1, 2, \dots, k$  and  $V_1, V_2, \dots, V_k$  are linearly independent. For  $m \in \{1, 2, \dots, k\}$ , let the operator  $V_m$  be represented by the matrix  $[(v_m)_{ij}]_{i,j=1,2,\dots,n}$ . Then  $\mathcal{V}$  is an interpolating subspace if and only if*

$$\begin{vmatrix} (x^{j_1} \otimes e_{j_1})(V_1) & \dots & (x^{j_1} \otimes e_{j_1})(V_k) \\ \vdots & \ddots & \vdots \\ (x^{j_k} \otimes e_{j_k})(V_1) & \dots & (x^{j_k} \otimes e_{j_k})(V_k) \end{vmatrix} \neq 0,$$

where  $(x^{j_l} \otimes e_{j_l}), (x^{j_r} \otimes e_{j_r}) \in \text{ext}S_{\mathcal{L}^*(l_1^n, l_1^n)}$  are linearly independent for  $l \neq r$ ,  $l, r \in \{1, 2, \dots, k\}$ .

*Proof.* This is a consequence of (2), the definition of a  $k$ -dimensional interpolating subspace and the theory of linear equations.  $\square$

**Example 1.** *Let  $V \in \mathcal{L}(l_1^n, l_1^n)$  be represented by a matrix  $[v_{ij}]_{i,j=1,2,\dots,n}$ , where  $v_{1j} = j$ ,  $v_{ij} = 0$ ,  $i = 2, \dots, n$ ,  $j = 1, 2, \dots, n$ . Then  $\mathcal{V} = \text{lin}\{V\}$  is a one-dimensional interpolating subspace.*

**Theorem 4.** Let  $\mathcal{V} = \text{lin}\{V\}$ ,  $V \in \mathcal{L}(l_1^n, l_1^n)$ ,  $n > 1$ ,  $V \neq 0$ ,  $V = [v_{ij}]_{i,j=1,2,\dots,n}$ .  $\mathcal{V}$  is a Chebyshev subspace of  $\mathcal{L}(l_1^n, l_1^n)$  if and only if  $\mathcal{V}$  is an interpolating subspace.

*Proof.* Let us assume that  $\mathcal{V}$  is not an interpolating subspace. Hence, there exists  $f = x^{j_0} \otimes e_{j_0}$ ,  $j_0 \in \{1, 2, \dots, n\}$ ,  $x^{j_0} = ((x^{j_0})_1, (x^{j_0})_2, \dots, (x^{j_0})_n)$ ,  $(x^{j_0})_i \in \{-1, 1\}$ ,  $i = 1, 2, \dots, n$ , such that  $f(V) = 0$ . Let us define  $A = [a_{ij}]_{i,j=1,2,\dots,n}$  as follows:

$$a_{ij_0} = -(x^{j_0})_i, \quad a_{ij} = 0, \quad j \neq j_0, \quad j \in \{1, 2, \dots, n\}, \quad i = 1, 2, \dots, n.$$

Note that  $\|A\| = n$ . Let us consider an operator  $A - \alpha V$ , where  $\alpha \in \mathbb{R}$ . For small enough  $\alpha$  we get  $\|A - \alpha V\| = \|A\|$ . The proof is complete.  $\square$

### 3. $k$ -DIMENSIONAL CHEBYSHEV SUBSPACES OF $\mathcal{L}(l_1^n, l_1^n)$

**Theorem 5.** Let  $\mathcal{V} = \text{lin}\{V_1, V_2, \dots, V_k\} \subset \mathcal{L}(l_1^n, l_1^n)$ ,  $k < n^2$ ,  $V_m \in \mathcal{L}(l_1^n, l_1^n)$  (where  $V_m$  are linearly independent for  $m = 1, 2, \dots, k$ ) be a  $k$ -dimensional subspace of  $\mathcal{L}(l_1^n, l_1^n)$ . Let  $V_m$ ,  $m \in \{1, 2, \dots, k\}$  be represented by a matrix  $[(v_m)_{ij}]_{i,j=1,2,\dots,n}$ . If  $\mathcal{V}$  is a Chebyshev subspace, then vectors  $w_1, w_2, \dots, w_h$  where

$$\begin{aligned} w_1 &= (f_1(V_1), \dots, f_1(V_k)), \\ w_2 &= (f_2(V_1), \dots, f_2(V_k)), \\ &\dots \\ w_h &= (f_h(V_1), \dots, f_h(V_k)) \end{aligned} \tag{3}$$

are linearly independent for any  $f_1, \dots, f_h \in \text{ext}S_{\mathcal{L}^*(l_1^n, l_1^n)}$  such that  $f_m = x^{j_m} \otimes e_{j_m}$ ,  $m = 1, 2, \dots, h$ ,  $j_m \neq j_r$  for  $m \neq r$ , where  $h = k$  if  $\dim \mathcal{V} = k \leq n$ ,  $h = n$  if  $n < \dim \mathcal{V} = k < n^2$ .

*Proof.* Let us assume that (3) does not hold. From this assumption there follows that there exist  $f_1, \dots, f_h \in \text{ext}S_{\mathcal{L}^*(l_1^n, l_1^n)}$  such that  $f_m = x^{j_m} \otimes e_{j_m}$ ,  $m = 1, 2, \dots, h$ , where  $j_m \neq j_r$  for  $m \neq r$  and  $w_1, w_2, \dots, w_h$  are linearly dependent. Hence, there exists  $l \in \{1, 2, \dots, h\}$  and there exist  $\gamma_p \in \mathbb{R}$ ,  $p \in \{1, 2, \dots, h\}$ , such that

$$(f_l(V_1), \dots, f_l(V_k)) = \sum_{p \in \{1, 2, \dots, h\}, p \neq l} \gamma_p (f_p(V_1), \dots, f_p(V_k)). \tag{4}$$

From (4) we obtain:

$$f_l(V_m) = \sum_{p \in \{1, 2, \dots, h\}, p \neq l} \gamma_p f_p(V_m), \quad m = 1, 2, \dots, k.$$

We shall construct an operator  $A \in \mathcal{L}(l_1^n, l_1^n)$  which has more than one best approximation in  $\mathcal{V}$ . Let  $[a_{ij}]_{i,j=1,2,\dots,n}$  be a matrix representation for  $A$ . If in (4),  $\gamma_p < 0$  for some  $p \in \{1, 2, \dots, h\}$ ,  $p \neq l$ , we put

$$a_{ij_p} = (x^{j_p})_i, \quad i = 1, 2, \dots, n.$$

If in (4),  $\gamma_p > 0$  for some  $p \in \{1, 2, \dots, h\}$ ,  $p \neq l$ , we put

$$a_{ij_p} = -(x^{j_p})_i, \quad i = 1, 2, \dots, n.$$

Additionally, we put

$$a_{ij_l} = (x^{j_l})_i, \quad i = 1, 2, \dots, n.$$

If  $j \neq j_p$ ,  $j \in \{1, 2, \dots, n\}$ , we put  $a_{ij} = 0$ ,  $i = 1, 2, \dots, n$ . Let us consider the operator

$$A(\alpha_1, \alpha_2, \dots, \alpha_k) := A - (\alpha_1 V_1 + \alpha_2 V_2 + \dots + \alpha_k V_k), \quad \text{where } \alpha_1, \alpha_2, \dots, \alpha_k \in \mathbb{R}.$$

For  $(\alpha_1, \alpha_2, \dots, \alpha_k) = (0, 0, \dots, 0)$  there is  $\|A(0, 0, \dots, 0)\| = \|A\|$ . As we have assumed that (3) does not hold, we conclude that there exists  $(\alpha_1, \alpha_2, \dots, \alpha_k) \neq (0, 0, \dots, 0)$  such that

$$\|A(\alpha_1, \alpha_2, \dots, \alpha_k)\| = \|A\|.$$

For  $\alpha_i$  small enough for  $i = 1, 2, \dots, k$ , the norm of the operator  $A(\alpha_1, \alpha_2, \dots, \alpha_k)$  is equal to the largest of the following values:

$$\|A\| - [\alpha_1 f_p(V_1) + \alpha_2 f_p(V_2) + \dots + \alpha_k f_p(V_k)],$$

for some  $p \in \{1, 2, \dots, h\}$ ,  $p \neq l$  for which  $\gamma_p < 0$ ;

$$\|A\| + [\alpha_1 f_p(V_1) + \alpha_2 f_p(V_2) + \dots + \alpha_k f_p(V_k)],$$

for some  $p \in \{1, 2, \dots, h\}$ ,  $p \neq l$  for which  $\gamma_p > 0$ ; or

$$\begin{aligned} & \|A\| - [\alpha_1 f_l(V_1) + \alpha_2 f_l(V_2) + \dots + \alpha_k f_l(V_k)] = \\ & = \|A\| - \left[ \sum_{p \in \{1, 2, \dots, h\}, p \neq l} \gamma_p (\alpha_1 f_p(V_1) + \dots + \alpha_k f_p(V_k)) \right]. \end{aligned} \quad (5)$$

From the above, if for some  $\alpha_1^0, \alpha_2^0, \dots, \alpha_k^0$  we want to obtain

$$\|A(\alpha_1^0, \alpha_2^0, \dots, \alpha_k^0)\| < \|A\|,$$

we need the inequality

$$[\alpha_1 f_p(V_1) + \alpha_2 f_p(V_2) + \dots + \alpha_k f_p(V_k)] > 0$$

to hold for  $p \in \{1, 2, \dots, h\}$ ,  $p \neq l$  for which  $\gamma_p < 0$ , and

$$[\alpha_1 f_p(V_1) + \alpha_2 f_p(V_2) + \dots + \alpha_k f_p(V_k)] < 0$$

for  $p \in \{1, 2, \dots, h\}$ ,  $p \neq l$  for which  $\gamma_p > 0$ . But then, by (5), we get

$$\|A(\alpha_1^0, \alpha_2^0, \dots, \alpha_k^0)\| > \|A\|.$$

□

Note that (3) is satisfied for any  $k$ -dimensional interpolating subspace. But the condition presented in Theorem 5 is not sufficient for a  $k$ -dimensional subspace ( $k \geq 2$ ) to be Chebyshev.

**Example 2.** Let  $\mathcal{V} = \text{lin}\{V_1, V_2\}$ , where

$$V_1 = \begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix}, \quad V_2 = \begin{bmatrix} 3 & 1 \\ 0 & 0 \end{bmatrix}.$$

Note that (3) is satisfied for  $\mathcal{V} = \text{lin}\{V_1, V_2\}$ . Let

$$A = \begin{bmatrix} 0 & 0 \\ 100 & 0 \end{bmatrix}.$$

Then  $\|A\| = 100$ . Let

$$A(\alpha_1, \alpha_2) := A - (\alpha_1 V_1 + \alpha_2 V_2) = \begin{bmatrix} -\alpha_1 - 3\alpha_2 & -2\alpha_1 - \alpha_2 \\ 100 & 0 \end{bmatrix}.$$

Hence, for  $(\alpha_1, \alpha_2) = (0, 0)$ , we get

$$\|A(\alpha_1, \alpha_2)\| = \|A\| = 100 = \inf_{\alpha_1, \alpha_2 \in \mathbb{R}} \|A(\alpha_1, \alpha_2)\|.$$

But for  $(\alpha_1, \alpha_2) = (3, -1)$  we get  $\|A(\alpha_1, \alpha_2)\| = \|A\| = 100$ .

Now we shall construct a  $k$ -dimensional Chebyshev subspace of  $\mathcal{L}(l_1^n, l_1^n)$  which is not an interpolating subspace.

**Theorem 6.** Let  $V_1, V_2, \dots, V_k \in \mathcal{L}(l_1^n, l_1^n)$ ,  $k \leq n$ ,  $n > 1$  be linearly independent and let  $V_m$ ,  $m \in \{1, 2, \dots, k\}$  be represented by a matrix

$$V_m = \begin{bmatrix} 0 & 0 & \cdot & \cdot & \cdot & 0 \\ 0 & 0 & \cdot & \cdot & \cdot & 0 \\ 0 & 0 & \cdot & \cdot & \cdot & 0 \\ v_{m1} & v_{m2} & \cdot & \cdot & \cdot & v_{mn} \\ 0 & 0 & \cdot & \cdot & \cdot & 0 \\ 0 & 0 & \cdot & \cdot & \cdot & 0 \end{bmatrix},$$

where  $v_{mj} \neq 0$  for any  $j = 1, 2, \dots, n$ ,  $m = 1, 2, \dots, k$ .  $\mathcal{V}(m_1, \dots, m_r) := \text{lin}\{V_{m_1}, \dots, V_{m_r}\}$ ,  $m_1, \dots, m_r \in \{1, 2, \dots, k\}$ ,  $m_p \neq m_q$ ,  $p \neq q$  is an  $r$ -dimensional Chebyshev subspace of  $\mathcal{L}(l_1^n, l_1^n)$  for any  $1 \leq r \leq k$  if and only if

$$\begin{aligned} & \text{for all } 1 \leq r \leq k, \quad 1 \leq j_1 < j_2 < \dots < j_r \leq n, \\ & 1 \leq i_1 < i_2 < \dots < i_r \leq k, \quad x^1, x^2, \dots, x^r \in \{-1, 1\}^r \text{ there is} \\ & \det[(x^m)_{i_m j_l}]_{m=1,2,\dots,r, l=1,2,\dots,r} \neq 0. \end{aligned} \tag{6}$$

*Proof.* Let us assume that (6) holds. If  $r = 1$ , then  $\mathcal{V}(m_1) = \text{lin}\{V_{m_1}\}$ ,  $m_1 \in \{1, 2, \dots, k\}$  is a Chebyshev subspace, because it is an interpolating subspace. Let us now assume that for  $1 < r < k$  the space

$$\begin{aligned} \mathcal{V}_r &:= \mathcal{V}(m_1, \dots, m_r) = \text{lin}\{V_{m_1}, \dots, V_{m_r}\}, \\ m_1, \dots, m_r &\in \{1, 2, \dots, k\}, \quad m_p \neq m_q, \quad p \neq q \end{aligned}$$

is a Chebyshev subspace of  $\mathcal{L}(l_1^n, l_1^n)$  and let

$$\begin{aligned} \mathcal{V}_{r+1} &:= \mathcal{V}(m_1, \dots, m_r, m_{r+1}) = \text{lin}\{V_{m_1}, \dots, V_{m_r}, V_{m_{r+1}}\}, \\ m_1, \dots, m_r &\in \{1, 2, \dots, k\}, \quad m_{r+1} \in \{1, 2, \dots, k\} \setminus \{m_1, \dots, m_r\} \end{aligned}$$

be not a Chebyshev subspace. From this we conclude that there exists an operator  $A \in \mathcal{L}(l_1^n, l_1^n)$  such that  $\# \mathcal{P}_{\mathcal{V}_{r+1}}(A) > 1$ . We can assume that  $0, W \in \mathcal{P}_{\mathcal{V}_{r+1}}(A)$ , where  $W \neq 0$ . Let  $\mathcal{U} := \{j \in \{1, 2, \dots, n\} : \|A \circ e_j^T\| = \|A\|\}$ , where  $e_j = (\delta_{1j}, \dots, \delta_{nj})$ . For any  $j \in \mathcal{U}$ , we put

$$E_j := \{x = (x_1, x_2, \dots, x_n) : x_i \in \{-1, 1\}, \quad i = 1, 2, \dots, n : (x \circ A)_j = \|A\|\}.$$

Since  $0, W \in \mathcal{P}_{\mathcal{V}_{r+1}}(A)$ , we conclude that for  $j \in \mathcal{U}$  and  $x \in E_j$  the following holds

$$(x \otimes e_j)(W) \geq 0. \quad (7)$$

Let

$$\mathcal{U}_1 := \{j \in \mathcal{U} : \exists x \in E_j : (x \otimes e_j)(W) = 0\}.$$

Since  $0 \in \mathcal{P}_{\mathcal{V}_{r+1}}(A)$ , then  $\mathcal{U}_1 \neq \emptyset$ . Now we shall show that

$$\forall j \in \mathcal{U}_1 \quad \exists! x \in E_j : (x \otimes e_j)(W) = 0. \quad (8)$$

Let us assume that (8) does not hold. Let  $x \neq y$ ,  $x, y \in E_j$  be such that

$$(x \otimes e_j)(W) = 0, \quad (y \otimes e_j)(W) = 0.$$

Without loss of generality, we may assume that

$$x_i = y_i, \quad i = 1, 2, \dots, p, \quad p < r + 1, \quad x_i = -y_i, \quad i = p + 1, p + 2, \dots, r + 1.$$

Then we get

$$\sum_{i=1}^p x_i(w)_{ij} = 0, \quad \sum_{i=p+1}^{r+1} x_i(w)_{ij} = 0. \quad (9)$$

Since  $x_i = -y_i$ ,  $i = p + 1, p + 2, \dots, r + 1$ , we obtain  $a_{ij} = 0$ ,  $i = p + 1, \dots, r + 1$ . By (7) there follows:

$$\begin{aligned} \sum_{i=p+1}^r x_i(w)_{ij} - x_{r+1}(w)_{r+1j} &\geq 0, \\ \sum_{i=p+1}^r -x_i(w)_{ij} + x_{r+1}(w)_{r+1j} &\geq 0, \end{aligned}$$

and then

$$\sum_{i=p+1}^r x_i(w)_{ij} = x_{r+1}(w)_{r+1j}.$$

Applying (9) we conclude that  $x_{r+1}(w)_{r+1j} = 0$  and then  $(w)_{r+1j} = 0$ . Hence  $W \in \mathcal{V}_r := \text{lin}\{V_{m_1}, \dots, V_{m_r}\}$ . Additionally,  $0 \in \mathcal{V}_r := \text{lin}\{V_{m_1}, \dots, V_{m_r}\}$ . But  $\mathcal{V}_r$  is a Chebyshev subspace and hence (8) is proved. We shall show that there exists  $\alpha_0 > 0$  such that for any  $0 < \alpha \leq \alpha_0$  the following holds:

$$E(A - \alpha W) = \{x \otimes e_j : j \in \mathcal{U}_1, (x \otimes e_j)(W) = 0, (x \otimes e_j)(A) = \|A\|\}. \quad (10)$$

Let  $f \notin E(A)$ . Then there exist  $\alpha_0 > 0$ ,  $b > 0$  such that for any  $0 < \alpha \leq \alpha_0$  the following holds:

$$f(A - \alpha W) \leq b < \|A\| \leq \|A - \alpha W\|.$$

Let  $f \in E(A - \alpha W)$ ,  $f(A) = \|A\|$ . If  $f(W) > 0$ , we get

$$\|A - \alpha W\| = f(A - \alpha W) = \|A\| - \alpha f(W) < \|A\|.$$

From the above we conclude that if  $f \in E(A - \alpha W)$ , then  $f \in E(A)$ ,  $f(W) = 0$ . Since

$$\|A - \alpha W\| = \|A\| = \text{dist}(A, \mathcal{V}_{r+1}),$$

(10) is proved. Since  $\alpha W \in \mathcal{P}_{\mathcal{V}_{r+1}}(A)$  we obtain (see [13]):

$$\exists 1 \leq q \leq r + 2, \exists \lambda_1, \dots, \lambda_q > 0, \sum_{i=1}^q \lambda_i = 1,$$

such that

$$\sum_{i=1}^q \lambda_i (x^{j_i} \otimes e_{j_i})|_{\mathcal{V}_{r+1}} = 0, \quad (11)$$

and  $(x^{j_i} \otimes e_{j_i})(A - \alpha W) = \|A - \alpha W\|$ . By (8) we get  $j_i \neq j_l$ ,  $i \neq l$ ,  $i, l \in \{1, 2, \dots, q\}$ . Let us take the least  $q$  such that  $1 \leq q \leq r + 2$  and (11) is satisfied. If  $q = r + 2$ , then (see [15]) we get that  $\alpha W$  is a strongly unique best approximation for  $A$  in  $\mathcal{V}_{r+1}$ . If  $1 \leq q \leq r + 1$ , we have a contradiction with (6).

Let us assume that  $\mathcal{V}_r = \text{lin}\{V_{m_1}, \dots, V_{m_r}\}$ ,  $m_1, \dots, m_r \in \{1, 2, \dots, k\}$ ,  $m_p \neq m_q$ ,  $p \neq q$  is a Chebyshev subspace of  $\mathcal{L}(l_1^n, l_1^n)$  for any  $1 \leq r \leq k$  and let (6) does not hold. Hence, there exist

$$1 \leq r \leq k, i_1, \dots, i_r, j_1, \dots, j_r \in \{1, 2, \dots, n\}, x^1, x^2, \dots, x^r \in \{-1, 1\}^n$$

such that

$$\det[(x^m)_{lv_{i_m j_l}}]_{m=1,2,\dots,r, l=1,2,\dots,r} = 0.$$

From this we conclude that there exist

$$\lambda_1, \dots, \lambda_r \in \mathbb{R}, \sum_{l=1}^r |\lambda_l| > 0$$



such that

$$\sum_{l=1}^r \lambda_l (x^{j_l} \otimes e_{j_l})|_{\mathcal{V}_r} = 0. \quad (12)$$

Without loss of generality, we may assume that  $\lambda_l > 0$ ,  $l = 1, 2, \dots, r$ . Let us now define an operator  $B = [b_{ij}]_{i,j=1,2,\dots,n}$  as follows:

$$b_{i j_l} = \text{sgn}(x^{j_l})_i, \quad b_{ij} = 0, \quad j \neq j_l, \quad l \in \{1, 2, \dots, r\}, \quad i \in \{1, 2, \dots, n\}.$$

Then  $(x^{j_l} \otimes e_{j_l})(B) = \|B\|$ ,  $l = 1, 2, \dots, r$ . By (12), there follows that  $0 \in \mathcal{P}_{\mathcal{V}_r}(B)$  and

$$\dim \text{span}\{x^{j_l} \otimes e_{j_l}|_{\mathcal{V}_r}\} < r,$$

where  $\dim \mathcal{V}_r = r$ . It means that there exists  $V \in \mathcal{V}_r \setminus \{0\}$  such that

$$(x^{j_l} \otimes e_{j_l})(V) = 0, \quad l = 1, 2, \dots, r.$$

Note that if  $f \notin E(B)$ , then there exist  $\alpha_0 > 0$ ,  $b > 0$  such that for any  $\alpha \in (0, \alpha_0)$ :

$$f(B - \alpha V) < \|B - \alpha V\|.$$

From the above we conclude that  $\|B - \alpha V\| = \|B\|$ .  $\square$

**Corollary 1.** *Let  $\mathcal{V} \subset \mathcal{L}(l_1^n, l_1^n)$  be a  $k$ -dimensional subspace from Theorem 6. Any operator  $A \in \mathcal{L}(l_1^n, l_1^n)$  has a unique best approximation in  $\mathcal{V}$  if and only if  $A$  has a strongly unique best approximation in  $\mathcal{V}$ .*

*Proof.* It is a consequence of [13] and the fact that  $\mathcal{L}(l_1^n, l_1^n)$  is a finite dimensional space.  $\square$

**Example 3.** *We shall construct a  $k$ -dimensional Chebyshev subspace  $\mathcal{V} \subset \mathcal{L}(l_1^n, l_1^n)$ ,  $k \leq n$ . The construction is as follows. Let  $0 < t_1 < t_2 < \dots < t_{k-1}$ . We put  $V_m = [(v_m)_{ij}]_{i,j=1,2,\dots,n}$ ,  $m = 1, 2, \dots, k-1$  as follows:*

$$\begin{aligned} (v_m)_{mj} &= t_m^j, \quad j = 1, 2, \dots, n, \\ (v_m)_{ij} &= 0, \quad i \neq m, \quad j = 1, 2, \dots, n. \end{aligned}$$

*Let us assume that the subspace  $\mathcal{V}_{k-1} := \text{lin}\{V_1, V_2, \dots, V_{k-1}\}$  satisfies formula (6) for any  $1 \leq r \leq k-1$ . We shall construct an operator  $V_k \in \mathcal{L}(l_1^n, l_1^n)$  such that  $\mathcal{V}_k := \text{lin}\{V_1, V_2, \dots, V_{k-1}, V_k\}$  satisfies formula (6) for any  $1 \leq r \leq k$ , which means that  $\mathcal{V}_k := \text{lin}\{V_1, V_2, \dots, V_{k-1}, V_k\}$  is a Chebyshev subspace of  $\mathcal{L}(l_1^n, l_1^n)$ . We are looking for such  $x \in \mathbb{R}$  that, for any  $r \in \{1, 2, \dots, k\}$ , there holds:*

$$W(x, y^1, \dots, y^r, j_1, \dots, j_r, m_1, \dots, m_{r-1}) := \begin{vmatrix} y_1^1 t_{m_1}^{j_1} & \cdot & \cdot & \cdot & y_1^r t_{m_1}^{j_r} \\ \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot \\ y_{r-1}^1 t_{m_{r-1}}^{j_1} & \cdot & \cdot & \cdot & y_{r-1}^r t_{m_{r-1}}^{j_r} \\ y_r^1 x^{j_1} & \cdot & \cdot & \cdot & y_r^r x^{j_r} \end{vmatrix} \neq 0, \quad (13)$$

for any  $j_1, j_2, \dots, j_r \in \{1, 2, \dots, n\}$ ,  $y^1, \dots, y^r \in \{-1, 1\}^r$ ,  $m_1, m_2, \dots, m_{r-1} \in \{1, 2, \dots, k-1\}$ .

By the assumption,  $W(x, y^1, \dots, y^r, j_1, \dots, j_r, m_1, \dots, m_{r-1})$  is not identically equal to zero. Hence, the set of roots of  $W(x, y^1, \dots, y^r, j_1, \dots, j_r, m_1, \dots, m_{r-1})$  is finite for arbitrary fixed  $y^1, \dots, y^r, j_1, \dots, j_r, m_1, \dots, m_{r-1}$ . Hence, the set of roots of  $W(x, y^1, \dots, y^r, j_1, \dots, j_r, m_1, \dots, m_{r-1})$ ,  $y^1, \dots, y^r, j_1, \dots, j_r, m_1, \dots, m_{r-1}$  is countable. But  $\mathbb{R}$  is not countable, so there exists  $x \in \mathbb{R}$  which satisfies (13).

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